

Attractors for a class of impulsive systems

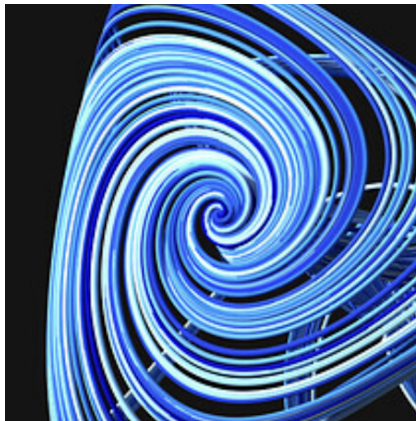
Everaldo de Mello Bonotto

Instituto de Ciências Matemáticas e de Computação
Universidade de São Paulo

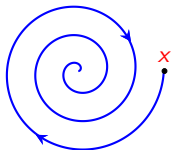
Workshop on PDEs and Control (PKM-60)

September 3, 2025

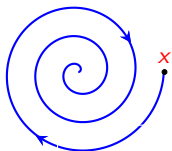
It is well known that to understand the asymptotic behavior of evolution equations the notion of **attractor** plays a central role.



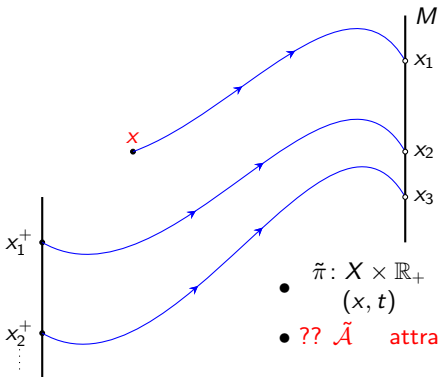
Attractor: a compact set which satisfies an invariance property and that attracts (in some sense) a class of subsets of the phase space in which the equation is stated.



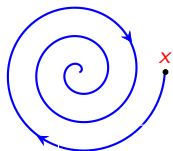
- $\pi: X \times \mathbb{R}_+ \rightarrow X$
 $(x, t) \mapsto \pi(x, t)$ flow
- \mathcal{A} attractor



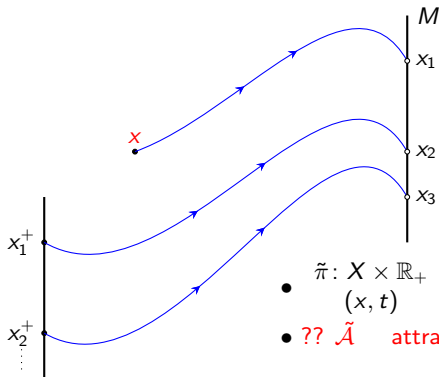
- $\pi: X \times \mathbb{R}_+ \rightarrow X$
 $(x, t) \mapsto \pi(x, t)$ flow
- \mathcal{A} attractor



- $\tilde{\pi}: X \times \mathbb{R}_+ \rightarrow X$
 $(x, t) \mapsto \tilde{\pi}(x, t)$ flow
- ?? $\tilde{\mathcal{A}}$ attractor ??



- $\pi: X \times \mathbb{R}_+ \rightarrow X$
 $(x, t) \mapsto \pi(x, t)$ flow
- \mathcal{A} attractor



- $\tilde{\pi}: X \times \mathbb{R}_+ \rightarrow X$
 $(x, t) \mapsto \tilde{\pi}(x, t)$ flow
- ?? $\tilde{\mathcal{A}}$ attractor ??

Does $\{x_1^+, x_2^+, x_3^+, \dots\}$ generate a discrete dynamical system? Attractor $\hat{\mathcal{A}}$?

If the attractors \mathcal{A} , $\tilde{\mathcal{A}}$, $\hat{\mathcal{A}}$ exist, are they related?



E. M. Bonotto, M. C. Bortolan, A. N. Carvalho, and R. Czaja, Global attractors for impulsive dynamical systems - a precompact approach, J. Differential Equations, 259 (2015), 2602–2625.



E. M. Bonotto, and J. M. Uzal, Global attractors for a class of discrete dynamical systems. J. Dynamics and Differential Equations, (2024).
<https://doi.org/10.1007/s10884-024-10356-9>

- 1 Impulsive Dynamical Systems
- 2 Global attractors for Impulsive Dynamical Systems
- 3 A class of Discrete Dynamical Systems
- 4 Relationship among the attractors \mathcal{A} , $\tilde{\mathcal{A}}$ and $\hat{\mathcal{A}}$.

- (X, d) is a complete metric space.

Definition 1.1

A **continuous semigroup** in X is a family of maps $\{\pi(t): t \geq 0\} \subset C(X)$, indexed on \mathbb{R}_+ , satisfying:

- $\pi(0) = I$;
- $\pi(t+s) = \pi(t)\pi(s)$ for all $t, s \in \mathbb{R}_+$;
- the map $\mathbb{R}_+ \times X \ni (t, x) \mapsto \pi(t)x$ is continuous.

For each $x \in X$, consider the map $\pi_x: \mathbb{R}_+ \rightarrow X$ given by $\pi_x(t) = \pi(t)x$ called the **trajectory** of x .

- (X, d) is a complete metric space.

Definition 1.1

A **continuous semigroup** in X is a family of maps $\{\pi(t): t \geq 0\} \subset C(X)$, indexed on \mathbb{R}_+ , satisfying:

- $\pi(0) = I$;
- $\pi(t+s) = \pi(t)\pi(s)$ for all $t, s \in \mathbb{R}_+$;
- the map $\mathbb{R}_+ \times X \ni (t, x) \mapsto \pi(t)x$ is continuous.

For each $x \in X$, consider the map $\pi_x: \mathbb{R}_+ \rightarrow X$ given by $\pi_x(t) = \pi(t)x$ called the **trajectory** of x .

Definition 1.2

An **impulsive dynamical system (IDS)**

$$(X, \pi, M, I)$$

consists of:

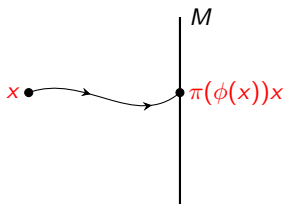
- a continuous semigroup $\{\pi(t) : t \geq 0\}$ in X ;
- a non-empty closed subset M of X (**called the impulsive set**) such that

for every $x \in M$, there is $\epsilon_x > 0$ such that
$$\bigcup_{t \in (0, \epsilon_x)} \{\pi(t)x\} \cap M = \emptyset;$$

- a continuous function $I : M \rightarrow X$ (**called the impulse function**).

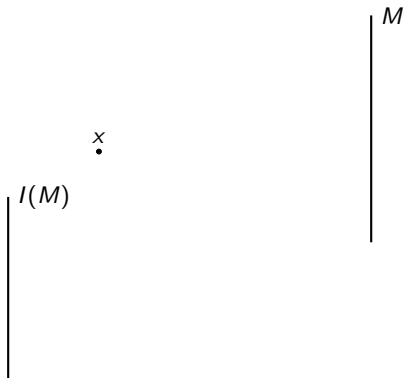
The **impact function** $\phi: X \rightarrow (0, \infty]$ is defined by

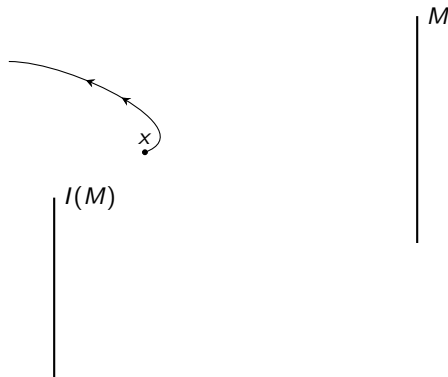
$$\phi(x) = \begin{cases} s, & \text{if } \pi(s)x \in M \text{ and } \pi(t)x \notin M \text{ for } 0 < t < s, \\ \infty, & \text{if } \pi(t)x \notin M \text{ for all } t > 0. \end{cases}$$



Impulsive semitrajectory of $x \in X$

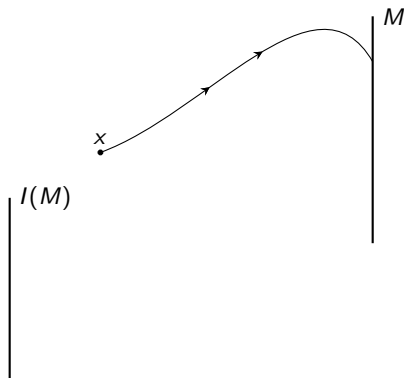
$$\begin{array}{rcl} \tilde{\pi}_x: & [0, T(x)) & \rightarrow X \\ & t & \mapsto \tilde{\pi}_x(t) \end{array}$$



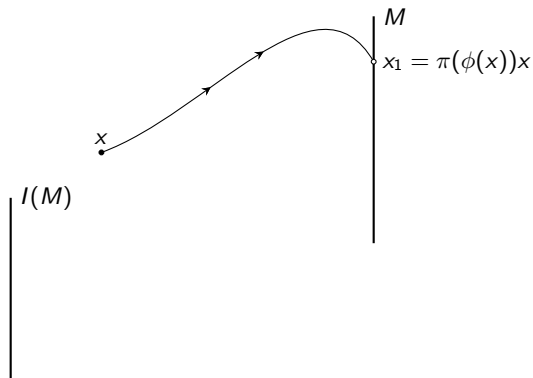


$$\phi(x) = \infty \quad \text{and} \quad \tilde{\pi}_x(t) = \pi(t)x \quad \text{for all} \quad t \geq 0.$$

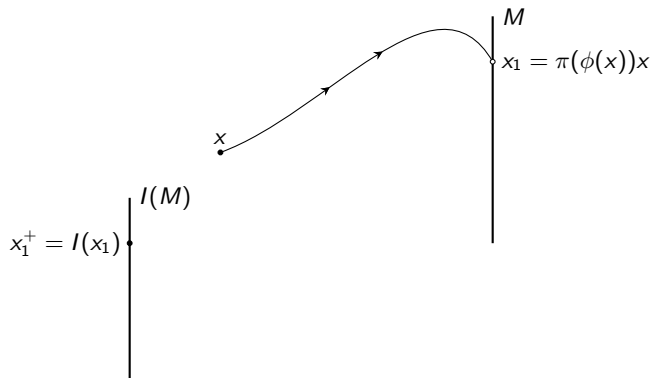
Impulsive semitrajectory

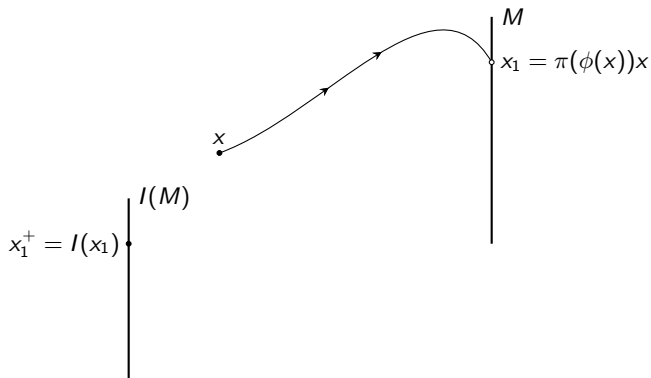


Impulsive semitrajectory



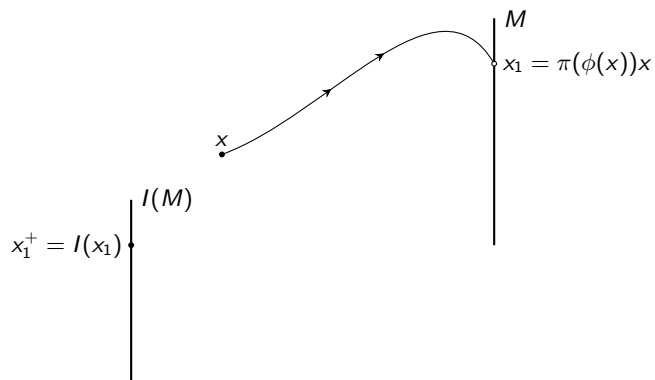
Impulsive semitrajectory



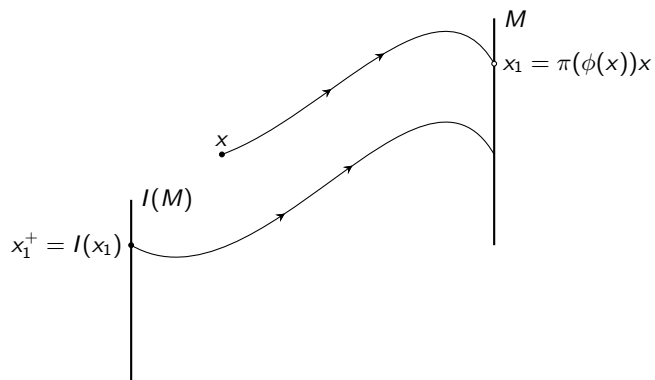


$$\phi(x) < \infty \quad \text{and} \quad \tilde{\pi}_x(t) = \begin{cases} \pi(t)x & \text{if } 0 \leq t < \phi(x) \\ x_1^+ & \text{if } t = \phi(x). \end{cases}$$

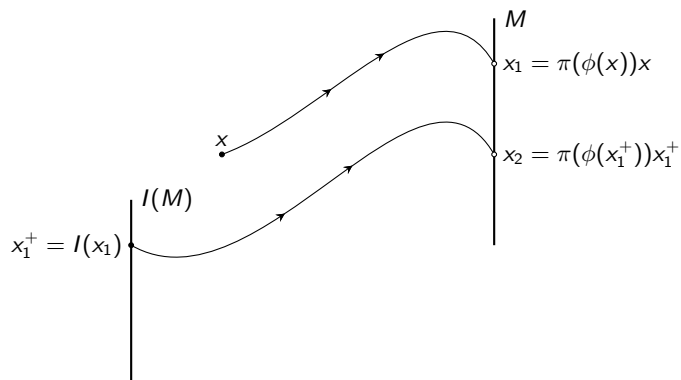
Impulsive semitrajectory

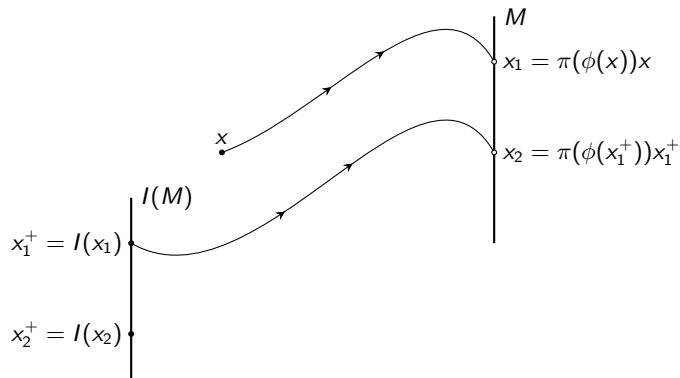


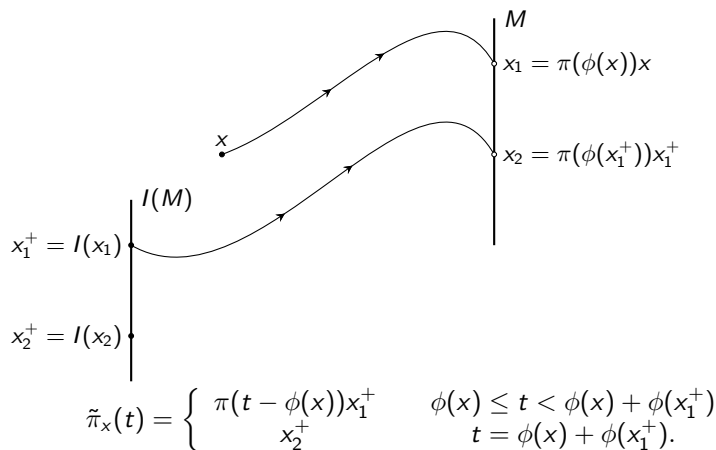
Impulsive semitrajectory



Impulsive semitrajectory







- We shall assume that $\tilde{\pi}_x$ is defined on $[0, \infty)$ for every $x \in X$.

- We shall assume that $\tilde{\pi}_x$ is defined on $[0, \infty)$ for every $x \in X$.
- Consider the family $\{\tilde{\pi}(t): t \geq 0\}$

$$\begin{array}{lll} \tilde{\pi}(t): & X & \rightarrow X \\ & x & \mapsto \tilde{\pi}(t)x = \tilde{\pi}_x(t) \end{array}$$

- We shall assume that $\tilde{\pi}_x$ is defined on $[0, \infty)$ for every $x \in X$.
- Consider the family $\{\tilde{\pi}(t): t \geq 0\}$

$$\begin{array}{lll} \tilde{\pi}(t): & X & \rightarrow X \\ & x & \mapsto \tilde{\pi}(t)x = \tilde{\pi}_x(t) \end{array}$$

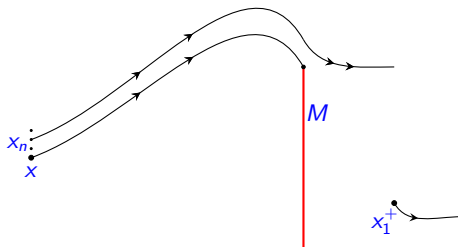
Proposition 1.3

Let (X, π, M, I) be an IDS. Then:

- (i) $\tilde{\pi}(0)x = x$ for all $x \in X$;
- (ii) $\tilde{\pi}(t)\tilde{\pi}(s)x = \tilde{\pi}(t+s)x$ for all $x \in X$ and $t, s \geq 0$

Question: Is it possible to obtain the convergence property $\tilde{\pi}(\phi(x))x_n \rightarrow \tilde{\pi}(\phi(x))x$?

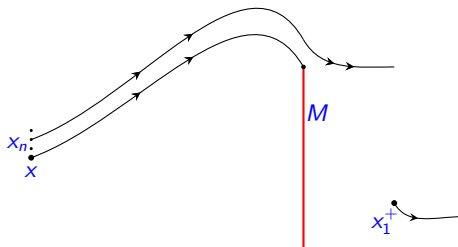
Question: Is it possible to obtain the convergence property $\tilde{\pi}(\phi(x))x_n \rightarrow \tilde{\pi}(\phi(x))x$?



Note that $x_n \xrightarrow{n \rightarrow \infty} x$ but

$$\tilde{\pi}(\phi(x))x_n \not\rightarrow \tilde{\pi}(\phi(x))x = x_1^+.$$

Question: Is it possible to obtain the convergence property $\tilde{\pi}(\phi(x))x_n \rightarrow \tilde{\pi}(\phi(x))x$?



Note that $x_n \xrightarrow{n \rightarrow \infty} x$ but

$$\tilde{\pi}(\phi(x))x_n \not\rightarrow \tilde{\pi}(\phi(x))x = x_1^+.$$

We shall assume that ϕ is continuous on $X \setminus M$.



Ciesielski, K.: On semicontinuity in impulsive dynamical systems, Bull. Polish Acad. Sci. Math., 52 (2004), 71-80.



Bonotto, E. M., Kalita, P.: On Attractors of Generalized Semiflows with Impulses, J. Geom. Anal., 30 (2020), 1412–1449.

We shall assume that ϕ is continuous on $X \setminus M$.



Ciesielski, K.: On semicontinuity in impulsive dynamical systems, Bull. Polish Acad. Sci. Math., 52 (2004), 71-80.



Bonotto, E. M., Kalita, P.: On Attractors of Generalized Semiflows with Impulses, J. Geom. Anal., 30 (2020), 1412–1449.

Lemma 1.4

Let $x \in X \setminus M$ and $t \geq 0$. Assume that $\{x_n\}_{n \in \mathbb{N}} \subset X$ is a sequence such that $x_n \xrightarrow{n \rightarrow \infty} x$. Then there is a sequence $\{\beta_n\}_{n \in \mathbb{N}} \subset \mathbb{R}_+$ such that $\beta_n \xrightarrow{n \rightarrow \infty} 0$ and

$$\tilde{\pi}(t + \beta_n)x_n \xrightarrow{n \rightarrow \infty} \tilde{\pi}(t)x.$$

- $A \subset X$ is **positively π -invariant** if $\pi^+(A) \subset A$.

- $A \subset X$ is **positively π -invariant** if $\pi^+(A) \subset A$.
- $A \subset X$ is **positively $\tilde{\pi}$ -invariant** if $\tilde{\pi}^+(A) \subset A$.

- $A \subset X$ is **positively π -invariant** if $\pi^+(A) \subset A$.
- $A \subset X$ is **positively $\tilde{\pi}$ -invariant** if $\tilde{\pi}^+(A) \subset A$.

If A is positively π -invariant then \overline{A} is positively π -invariant.

- $A \subset X$ is **positively π -invariant** if $\pi^+(A) \subset A$.
- $A \subset X$ is **positively $\tilde{\pi}$ -invariant** if $\tilde{\pi}^+(A) \subset A$.

If A is positively π -invariant then \overline{A} is positively π -invariant. But, this result is not valid in general for impulsive systems.

- $A \subset X$ is **positively π -invariant** if $\pi^+(A) \subset A$.
- $A \subset X$ is **positively $\tilde{\pi}$ -invariant** if $\tilde{\pi}^+(A) \subset A$.

If A is positively π -invariant then \overline{A} is positively π -invariant. But, this result is not valid in general for impulsive systems.

In fact, let (\mathbb{R}, π, M, I) be an IDS given by $\pi(t)x = x + t$, for $(x, t) \in \mathbb{R} \times \mathbb{R}_+$, $M = \{1\}$ and $I(1) = 0$.



- $A \subset X$ is **positively π -invariant** if $\pi^+(A) \subset A$.
- $A \subset X$ is **positively $\tilde{\pi}$ -invariant** if $\tilde{\pi}^+(A) \subset A$.

If A is positively π -invariant then \overline{A} is positively π -invariant. But, this result is not valid in general for impulsive systems.

In fact, let (\mathbb{R}, π, M, I) be an IDS given by $\pi(t)x = x + t$, for $(x, t) \in \mathbb{R} \times \mathbb{R}_+$, $M = \{1\}$ and $I(1) = 0$.



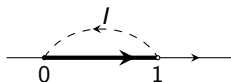
The set $A = [0, 1)$ is positively $\tilde{\pi}$ -invariant, but $\overline{A} = [0, 1]$ is not positively $\tilde{\pi}$ -invariant.

$$\tilde{\pi}^+(\overline{A}) = [0, \infty).$$

- $A \subset X$ is **positively π -invariant** if $\pi^+(A) \subset A$.
- $A \subset X$ is **positively $\tilde{\pi}$ -invariant** if $\tilde{\pi}^+(A) \subset A$.

If A is positively π -invariant then \overline{A} is positively π -invariant. But, this result is not valid in general for impulsive systems.

In fact, let (\mathbb{R}, π, M, I) be an IDS given by $\pi(t)x = x + t$, for $(x, t) \in \mathbb{R} \times \mathbb{R}_+$, $M = \{1\}$ and $I(1) = 0$.



The set $A = [0, 1)$ is positively $\tilde{\pi}$ -invariant, but $\overline{A} = [0, 1]$ is not positively $\tilde{\pi}$ -invariant.

$$\tilde{\pi}^+(\overline{A}) = [0, \infty).$$

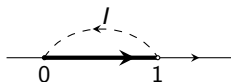
Lemma 1.5

Let $B \subset X$ be a positively $\tilde{\pi}$ -invariant set. Then $\overline{B} \setminus M$ is positively $\tilde{\pi}$ -invariant.

- $A \subset X$ is **positively π -invariant** if $\pi^+(A) \subset A$.
- $A \subset X$ is **positively $\tilde{\pi}$ -invariant** if $\tilde{\pi}^+(A) \subset A$.

If A is positively π -invariant then \overline{A} is positively π -invariant. But, this result is not valid in general for impulsive systems.

In fact, let (\mathbb{R}, π, M, I) be an IDS given by $\pi(t)x = x + t$, for $(x, t) \in \mathbb{R} \times \mathbb{R}_+$, $M = \{1\}$ and $I(1) = 0$.



The set $A = [0, 1)$ is positively $\tilde{\pi}$ -invariant, but $\overline{A} = [0, 1]$ is not positively $\tilde{\pi}$ -invariant.

$$\tilde{\pi}^+(\overline{A}) = [0, \infty).$$

Lemma 1.5

Let $B \subset X$ be a positively $\tilde{\pi}$ -invariant set. Then $\overline{B} \setminus M$ is positively $\tilde{\pi}$ -invariant.

- 1 Impulsive Dynamical Systems
- 2 Global attractors for Impulsive Dynamical Systems
- 3 A class of Discrete Dynamical Systems
- 4 Relationship among the attractors \mathcal{A} , $\tilde{\mathcal{A}}$ and $\hat{\mathcal{A}}$.

Definition 2.1

A subset $\mathcal{A} \subset X$ will be called a **global attractor** for the semigroup $\{\pi(t) : t \geq 0\}$ if it satisfies the following conditions:

- (i) \mathcal{A} is **compact**;
- (ii) \mathcal{A} is **π -invariant** ($\pi(t)\mathcal{A} = \mathcal{A}$ for all $t \in \mathbb{R}_+$);
- (iii) \mathcal{A} **π -attracts** bounded subsets of X $\left(\lim_{t \rightarrow \infty} d_H(\pi(t)B, \mathcal{A}) = 0, \forall B \in \mathcal{B}(X) \right)$.

Definition 2.1

A subset $\mathcal{A} \subset X$ will be called a **global attractor** for the semigroup $\{\pi(t) : t \geq 0\}$ if it satisfies the following conditions:

- (i) \mathcal{A} is **compact**;
- (ii) \mathcal{A} is π -**invariant** ($\pi(t)\mathcal{A} = \mathcal{A}$ for all $t \in \mathbb{R}_+$);
- (iii) \mathcal{A} π -**attracts** bounded subsets of X ($\lim_{t \rightarrow \infty} d_H(\pi(t)B, \mathcal{A}) = 0, \forall B \in \mathcal{B}(X)$).

Definition 2.2

A subset $\tilde{\mathcal{A}} \subset X$ will be called a **global attractor** for the IDS (X, π, M, I) if it satisfies the following conditions:

- (i) $\tilde{\mathcal{A}}$ is **precompact** and $\tilde{\mathcal{A}} = \overline{\tilde{\mathcal{A}}} \setminus M$;
- (ii) $\tilde{\mathcal{A}}$ is $\tilde{\pi}$ -**invariant** ($\tilde{\pi}(t)\tilde{\mathcal{A}} = \tilde{\mathcal{A}}$ for all $t \in \mathbb{R}_+$);
- (iii) $\tilde{\mathcal{A}}$ $\tilde{\pi}$ -**attracts** bounded subsets of X ($\lim_{t \rightarrow \infty} d_H(\tilde{\pi}(t)B, \tilde{\mathcal{A}}) = 0, \forall B \in \mathcal{B}(X)$).

- If $\tilde{\mathcal{A}}$ exists, then it is uniquely determined.
- If $M = \emptyset$, then the definitions coincide.

Definition 2.3

An IDS (X, π, M, I) is called **asymptotically compact**, if given a set $B \in \mathcal{B}(X)$, a sequence $\{t_n\}_{n \in \mathbb{N}} \subset \mathbb{R}_+$ with $t_n \rightarrow \infty$, and a sequence $\{x_n\}_{n \in \mathbb{N}} \subset B$, then the sequence $\{\tilde{\pi}(t_n)x_n\}_{n \in \mathbb{N}}$ possesses a convergent subsequence in X .

Definition 2.3

An IDS (X, π, M, I) is called **asymptotically compact**, if given a set $B \in \mathcal{B}(X)$, a sequence $\{t_n\}_{n \in \mathbb{N}} \subset \mathbb{R}_+$ with $t_n \rightarrow \infty$, and a sequence $\{x_n\}_{n \in \mathbb{N}} \subset B$, then the sequence $\{\tilde{\pi}(t_n)x_n\}_{n \in \mathbb{N}}$ possesses a convergent subsequence in X .

Definition 2.4

An IDS (X, π, M, I) is called **dissipative**, if there exists a set $B_0 \in \mathcal{B}(X)$, called absorbing set, such that for every $B \in \mathcal{B}(X)$ there exists a time $T_B \geq 0$ such that $\tilde{\pi}(t)B \subset B_0$ for all $t \geq T_B$.

Definition 2.3

An IDS (X, π, M, I) is called **asymptotically compact**, if given a set $B \in \mathcal{B}(X)$, a sequence $\{t_n\}_{n \in \mathbb{N}} \subset \mathbb{R}_+$ with $t_n \rightarrow \infty$, and a sequence $\{x_n\}_{n \in \mathbb{N}} \subset B$, then the sequence $\{\tilde{\pi}(t_n)x_n\}_{n \in \mathbb{N}}$ possesses a convergent subsequence in X .

Definition 2.4

An IDS (X, π, M, I) is called **dissipative**, if there exists a set $B_0 \in \mathcal{B}(X)$, called absorbing set, such that for every $B \in \mathcal{B}(X)$ there exists a time $T_B \geq 0$ such that $\tilde{\pi}(t)B \subset B_0$ for all $t \geq T_B$.

Theorem 2.5

An IDS (X, π, M, I) admits a global attractor $\tilde{\mathcal{A}}$ if and only if it is asymptotically compact and dissipative.

$$\tilde{\mathcal{A}} = \tilde{\omega}(B_0) \setminus M,$$

$$\text{where } \tilde{\omega}(B_0) = \bigcap_{t \geq 0} \overline{\bigcup_{\tau \geq t} \tilde{\pi}(\tau)B_0}.$$

- 1 Impulsive Dynamical Systems
- 2 Global attractors for Impulsive Dynamical Systems
- 3 A class of Discrete Dynamical Systems
- 4 Relationship among the attractors \mathcal{A} , $\tilde{\mathcal{A}}$ and $\hat{\mathcal{A}}$.

A discrete dynamical system

Assume that:

- (H1) ϕ is continuous on $X \setminus M$;
- (H2) there exists $z \in I(M)$ such that $\phi(z_k^+) < \infty$ for all $k \in \mathbb{N}$;
- (H3) $I(M) \cap M = \emptyset$.

A discrete dynamical system

Assume that:

- (H1) ϕ is continuous on $X \setminus M$;
- (H2) there exists $z \in I(M)$ such that $\phi(z_k^+) < \infty$ for all $k \in \mathbb{N}$;
- (H3) $I(M) \cap M = \emptyset$.

Consider the set

$$\hat{X} = \{x \in I(M) : \phi(x_k^+) < \infty \text{ for all } k \in \mathbb{N}\}$$

and the map $g: \hat{X} \rightarrow \hat{X}$ given by

$$g(x) = I(\pi(\phi(x))x). \tag{1}$$

A discrete dynamical system

Assume that:

- (H1) ϕ is continuous on $X \setminus M$;
- (H2) there exists $z \in I(M)$ such that $\phi(z_k^+) < \infty$ for all $k \in \mathbb{N}$;
- (H3) $I(M) \cap M = \emptyset$.

Consider the set

$$\hat{X} = \{x \in I(M) : \phi(x_k^+) < \infty \text{ for all } k \in \mathbb{N}\}$$

and the map $g: \hat{X} \rightarrow \hat{X}$ given by

$$g(x) = I(\pi(\phi(x))x). \quad (1)$$

- Condition (H2) $\implies \hat{X} \neq \emptyset$.

A discrete dynamical system

Assume that:

- (H1) ϕ is continuous on $X \setminus M$;
- (H2) there exists $z \in I(M)$ such that $\phi(z_k^+) < \infty$ for all $k \in \mathbb{N}$;
- (H3) $I(M) \cap M = \emptyset$.

Consider the set

$$\hat{X} = \{x \in I(M) : \phi(x_k^+) < \infty \text{ for all } k \in \mathbb{N}\}$$

and the map $g: \hat{X} \rightarrow \hat{X}$ given by

$$g(x) = I(\pi(\phi(x))x). \quad (1)$$

- Condition (H2) $\implies \hat{X} \neq \emptyset$.
- The map g is continuous on \hat{X} .

A discrete dynamical system

Assume that:

- (H1) ϕ is continuous on $X \setminus M$;
- (H2) there exists $z \in I(M)$ such that $\phi(z_k^+) < \infty$ for all $k \in \mathbb{N}$;
- (H3) $I(M) \cap M = \emptyset$.

Consider the set

$$\hat{X} = \{x \in I(M) : \phi(x_k^+) < \infty \text{ for all } k \in \mathbb{N}\}$$

and the map $g: \hat{X} \rightarrow \hat{X}$ given by

$$g(x) = I(\pi(\phi(x))x). \quad (1)$$

- Condition (H2) $\implies \hat{X} \neq \emptyset$.
- The map g is continuous on \hat{X} .
- (\hat{X}, g) defines a discrete dynamical system on \hat{X} :

$$g^0(x) = x \quad \text{and} \quad g^n(x) = x_n^+ \quad \text{for all } x \in \hat{X}, n \in \mathbb{N}.$$

A discrete dynamical system

Assume that:

- (H1) ϕ is continuous on $X \setminus M$;
- (H2) there exists $z \in I(M)$ such that $\phi(z_k^+) < \infty$ for all $k \in \mathbb{N}$;
- (H3) $I(M) \cap M = \emptyset$.

Consider the set

$$\hat{X} = \{x \in I(M) : \phi(x_k^+) < \infty \text{ for all } k \in \mathbb{N}\}$$

and the map $g: \hat{X} \rightarrow \hat{X}$ given by

$$g(x) = I(\pi(\phi(x))x). \quad (1)$$

- Condition (H2) $\implies \hat{X} \neq \emptyset$.
- The map g is continuous on \hat{X} .
- (\hat{X}, g) defines a discrete dynamical system on \hat{X} :

$$g^0(x) = x \quad \text{and} \quad g^n(x) = x_n^+ \quad \text{for all } x \in \hat{X}, n \in \mathbb{N}.$$

Definition 3.1

A subset $\hat{B} \subset \hat{X}$ is said to be:

- (i) **positively g -invariant** w.r.t. (\hat{X}, g) , if $g(\hat{B}) \subset \hat{B}$;
- (ii) **negatively g -invariant** w.r.t. (\hat{X}, g) , if $g(\hat{B}) \supset \hat{B}$;
- (iii) **g -invariant** if it is both positively and negatively g -invariant w.r.t. (\hat{X}, g) .

Definition 3.2

The **omega limit set** of a subset $\hat{B} \subset \hat{X}$ is given by

$$\hat{\omega}(\hat{B}) = \{x \in \hat{X} : \text{there exist sequences } \{x_k\}_{k \in \mathbb{N}} \subset \hat{B} \text{ and } \{n_k\}_{k \in \mathbb{N}} \subset \mathbb{N} \\ \text{with } n_k \rightarrow \infty \text{ such that } g^{n_k}(x_k) \rightarrow x\}.$$

Let $\mathcal{B}(\hat{X})$ denote the set of all bounded subsets from \hat{X} .

Definition 3.3

A set $\hat{\mathcal{A}} \subset \hat{X}$ is called a **discrete global attractor** for (\hat{X}, g) if:

- (i) $\hat{\mathcal{A}}$ is compact;
- (ii) $\hat{\mathcal{A}}$ is g -invariant;
- (iii) $d_H(g^n(\hat{B}), \hat{\mathcal{A}}) \rightarrow 0$ for every $\hat{B} \in \mathcal{B}(\hat{X})$.

Let $\mathcal{B}(\hat{X})$ denote the set of all bounded subsets from \hat{X} .

Definition 3.3

A set $\hat{\mathcal{A}} \subset \hat{X}$ is called a **discrete global attractor** for (\hat{X}, g) if:

- (i) $\hat{\mathcal{A}}$ is compact;
- (ii) $\hat{\mathcal{A}}$ is g -invariant;
- (iii) $d_H(g^n(\hat{B}), \hat{\mathcal{A}}) \rightarrow 0$ for every $\hat{B} \in \mathcal{B}(\hat{X})$.

Theorem 3.4

Assume that (X, π, M, I) satisfies conditions (H1)-(H3) and (\hat{X}, g) is *asymptotically compact* and *bounded dissipative* with absorbing set \hat{B}_0 . Then (\hat{X}, g) has a discrete global attractor $\hat{\mathcal{A}}$ given by $\hat{\mathcal{A}} = \hat{\omega}(\hat{B}_0)$.

- 1 Impulsive Dynamical Systems
- 2 Global attractors for Impulsive Dynamical Systems
- 3 A class of Discrete Dynamical Systems
- 4 Relationship among the attractors \mathcal{A} , $\tilde{\mathcal{A}}$ and $\hat{\mathcal{A}}$.

- semigroup $\{\pi(t): t \geq 0\}$ with global attractor \mathcal{A} .
- IDS (X, π, M, I) with global attractor $\tilde{\mathcal{A}}$.
- DDS (\hat{X}, g) with discrete global attractor $\hat{\mathcal{A}}$.

Example 1

Consider the system of differential equations

$$\begin{cases} x' = -x, \\ y' = -y, \end{cases}$$

in $X = \mathbb{R}^2$. In this simple example, $\mathcal{A} = \{(0, 0)\}$.

- (a) If $M = \bigcup_{n \in \mathbb{N}} M_n$ with $M_n = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 = n^2\}$, $n = 1, 2, \dots$, and $I(x, y) = (x(1 + \frac{1}{2n}), y(1 + \frac{1}{2n}))$ for $(x, y) \in M_n$, $n = 1, 2, \dots$, then the systems (X, π, M, I) and (\hat{X}, g) do not admit global attractors.
- (b) If $M = \bigcup_{n \in \mathbb{N}} M_n$ with $M_n = \{(x, y) \in \mathbb{R}^2 : x^2 + y^2 = n^2\}$, $n = 1, 2, \dots$, and $I(x, y) = (\frac{x}{2n}, \frac{y}{2n})$ for all $(x, y) \in M_n$, $n = 1, 2, \dots$. Then $\tilde{\mathcal{A}} = \mathcal{A}$ and $\hat{X} = \emptyset$.
- (c) If $M = \mathbb{R} \times \{1\}$ and $I(x, 1) = (\tan^{-1}(x), 2)$, $x \in \mathbb{R}$. Then $\hat{\mathcal{A}} = \{(0, 2)\}$ and $\tilde{\mathcal{A}} = \{(0, y) : 1 < y \leq 2\} \cup \{(0, 0)\}$. Note that $\hat{X} = I(M) = (-\frac{\pi}{2}, \frac{\pi}{2}) \times \{2\}$. Moreover,

$$\tilde{\mathcal{A}} = \pi([0, \ln 2)) \cdot \hat{\mathcal{A}} \cup \mathcal{A}.$$

- $I(M) \cap M = \emptyset$

Proposition 4.1

Assume that $\{\pi(t): t \geq 0\}$ has a global attractor \mathcal{A} with $\mathcal{A} \cap M = \emptyset$ and (X, π, M, I) has a global attractor $\tilde{\mathcal{A}}$. Then $\mathcal{A} \subset \tilde{\mathcal{A}}$.

- $I(M) \cap M = \emptyset$

Proposition 4.1

Assume that $\{\pi(t): t \geq 0\}$ has a global attractor \mathcal{A} with $\mathcal{A} \cap M = \emptyset$ and (X, π, M, I) has a global attractor $\tilde{\mathcal{A}}$. Then $\mathcal{A} \subset \tilde{\mathcal{A}}$.

Proposition 4.2

Assume that (X, π, M, I) has a global attractor $\tilde{\mathcal{A}}$ and (\hat{X}, g) has a discrete global attractor $\hat{\mathcal{A}}$. Then $\hat{\mathcal{A}} \subset \tilde{\mathcal{A}}$.

Attractors \mathcal{A} , $\tilde{\mathcal{A}}$ and $\hat{\mathcal{A}}$

- $I(M) \cap M = \emptyset$

Proposition 4.1

Assume that $\{\pi(t): t \geq 0\}$ has a global attractor \mathcal{A} with $\mathcal{A} \cap M = \emptyset$ and (X, π, M, I) has a global attractor $\tilde{\mathcal{A}}$. Then $\mathcal{A} \subset \tilde{\mathcal{A}}$.

Proposition 4.2

Assume that (X, π, M, I) has a global attractor $\tilde{\mathcal{A}}$ and (\hat{X}, g) has a discrete global attractor $\hat{\mathcal{A}}$. Then $\hat{\mathcal{A}} \subset \tilde{\mathcal{A}}$.

Theorem 4.3

Assume that $\{\pi(t): t \geq 0\}$ admits a global attractor \mathcal{A} with $\mathcal{A} \cap M = \emptyset$, (\hat{X}, g) has a global attractor $\hat{\mathcal{A}}$, (X, π, M, I) is dissipative and $\phi(x) < \infty$ for all $x \in I(M)$. Then (X, π, M, I) admits a global attractor $\tilde{\mathcal{A}}$ given by

$$\tilde{\mathcal{A}} = \mathcal{A} \cup \left(\bigcup_{a \in \hat{\mathcal{A}}} \pi([0, \phi(a)))a \right).$$

Consider the nonlinear reaction-diffusion initial boundary value problem

$$\begin{cases} u_t - \Delta u = f(u) & \text{for } (x, t) \in \Omega \times (0, \infty), \\ u(x, t) = 0, & \text{for } (x, t) \in \partial\Omega \times (0, \infty), \\ u(x, 0) = u_0(x), & \text{for } x \in \Omega, \end{cases} \quad (2)$$

where Ω is a bounded smooth domain of \mathbb{R}^n ($n \geq 2$) with smooth boundary and Δ is the Laplace operator in Ω . The nonlinearity $f: \mathbb{R} \rightarrow \mathbb{R}$ satisfies the growth and dissipative conditions:

(a) $|f(t) - f(s)| \leq c|t - s|$, for all $t, s \in \mathbb{R}$, where $c > 0$;

(b) $\limsup_{|s| \rightarrow \infty} \frac{f(s)}{s} < \lambda_1$.

For each $u_0 \in L^2(\Omega)$, $\exists!$ solution u of (2) with $u \in C([0, \infty), L^2(\Omega))$ such that the map $u_0 \mapsto u(t)$ is continuous in $L^2(\Omega)$. Thus, the map $\pi(t): L^2(\Omega) \rightarrow L^2(\Omega)$ given by

$$\pi(t)u_0 = u(t)$$

defines a dynamical system $(L^2(\Omega), \pi)$ on $L^2(\Omega)$.

- The dynamical system $(L^2(\Omega), \pi)$ is dissipative with absorbing set

$$B_0 = \left\{ v \in L^2(\Omega) : \|v\|_2 \leq \frac{\rho_0 C |\Omega|}{\epsilon_0} \right\}, \quad \rho_0 > 1, \epsilon_0 > 0.$$

- $(L^2(\Omega), \pi)$ admits a global attractor \mathcal{A} .
- Let $r_0 > \max \left\{ 1, \frac{2\rho_0 C |\Omega|}{\epsilon_0} \right\}$. Consider the set $M = \{v \in L^2(\Omega) : \|v\|_2 = r_0\}$ and a continuous function $I: M \rightarrow L^2(\Omega)$.
- If $\|I(z)\|_2 < \|z\|_2$ for all $z \in M$ then $\tilde{\mathcal{A}} = \mathcal{A}$ and $\hat{\mathcal{A}}$ does not exist.

The operator $-\Delta$ with the Dirichlet boundary conditions admits an orthonormal complete sequence of eigenfunctions $\{e_i\}_{i=1}^{\infty}$ in $L^2(\Omega)$ with corresponding eigenvalues $\{\lambda_i\}_{i=1}^{\infty}$ satisfying $0 < \lambda_1 \leq \lambda_2 \leq \dots \leq \lambda_n \leq \dots$, $\lambda_n \rightarrow \infty$.

$$\pi(t)u_0 = u(t) = \sum_{i=1}^{\infty} \alpha_i(t)e_i.$$

where $\alpha_i(t)$ (Fourier coefficient) satisfies the ODE $\alpha_i'(t) + \lambda_i \alpha_i(t) = (f(u(t)), e_i)$, $i \in \mathbb{N}$.

- If $I(v) = v + 3r_0 e_1$ for all $v \in M$, then

$$\tilde{\mathcal{A}} = \mathcal{A} \cup \left(\bigcup_{a \in \hat{\mathcal{A}}} \pi([0, \phi(a)))a \right).$$

Thank you for your attention!

¡Feliz cumpleaños, Kisko y Manolo!